



RELIABILITY-BASED DESIGN OPTIMIZATION OF LARGE-SCALE COMPLEX SYSTEMS

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INTRODUCTION

- What is RBDO?

$$\min_{\theta} h_0(\theta) := \mathbb{E}_{\theta}[y_0(\mathbf{X})], \\ \text{subject to } h_k(\theta) := \mathbb{P}_{\theta}[\mathbf{X} \in \Omega_{F,k}] \leq p_k; k = 1, \dots, K$$

$\theta \in \mathcal{D} \subseteq \mathbb{R}^M \rightarrow M\text{-dim. design vector}; \Omega_{F,k} \rightarrow \text{failure domain}$

$\mathbf{X} \in \mathbb{R}^N \rightarrow N\text{-dim. input random vector} \sim f_{\mathbf{X}}(\mathbf{x}; \theta)$

$\mathbb{B}_{\theta}: f_{\mathbf{X}} \rightarrow \mathbb{R}; P_{\theta}: f_{\mathbf{X}} \rightarrow [0, 1]; y_k(\mathbf{x}) \rightarrow \text{performance function}$

Type	Failure Domain	Application
Component	$\Omega_{F,k} := \{\mathbf{x} : y_k(\mathbf{x}) < 0\}$	Single failure event
Series System	$\Omega_{F,k} := \{\mathbf{x} : \bigcup_q y_k^{(q)}(\mathbf{x}) < 0\}$	Union of failure events
Parallel System	$\Omega_{F,k} := \{\mathbf{x} : \bigcap_q y_k^{(q)}(\mathbf{x}) < 0\}$	Intersection of failure events
General System	$\Omega_{F,k} := \{\mathbf{x} : \bigcup_{l \in C_k} \bigcap_{q \in C_l} y_k^{(q)}(\mathbf{x}) < 0\}$	Certain comb. of fail events

NEW X-PDD METHOD

- Three-Term Recurrence Relation (OG Polynomials)

$$\pi_{i,j+1}(x_i) = (x_i - a_{ij})\pi_{ij}(x_i) - b_{ij}\pi_{i,j-1}(x_i); \psi_{ij}(x_i) := \pi_{ij}/\|\pi_{ij}\|_{dF_i}$$

Measure ^(a)	$a_{ij}, j \geq 0$	$b_{ij}, j \geq 1$
Gaussian (Hermite)	0	
Uniform (Legendre)	0	$\frac{1}{(4-j^2)}$
Exponential (Laguerre)	$2j+1$	j^2
Gamma (Gen. Laguerre)	$2j+\alpha+1$	$j(j+\alpha)$
Beta (Jacobi)	$\frac{(\beta^2-\alpha^2)}{(2j+\alpha+\beta)(2j+\alpha+\beta+2)}$	$\frac{4j(j+\alpha)(j+\beta)}{(2j+\alpha+\beta)^2} \times$ $\frac{[(2j+\alpha+\beta)^2-1]}{[(j+\alpha+\beta)^2-1]}$
Lognormal (?)	$\exp[-\frac{1}{2}\hat{\sigma}^2(2j-1)] \times$ $\exp(\hat{\sigma}^2)[\exp(\hat{\sigma}^2)+1]-1$	$\exp[2\hat{\sigma}^2(3j-2)] \times$ $\exp[j(\hat{\sigma}^2)-1]$
Student's t (?)	0	$\frac{j\nu(\nu-j+1)}{[(\nu-2j)(\nu-2j+2)(\nu-2j+4)]}$
Fisher's F (?)	$\frac{(\nu_1\nu_2+2\nu_1+4\nu_2-8j^2)\times}{(\nu_2-4j-2)(\nu_2-4j+2)}$	$\frac{2j(\nu_1+\nu_2-4j+2)^2}{(\nu_2-4j)(\nu_2-4j+2)} \times$ $\frac{[(\nu_2-4j)(\nu_2-4j+2)^2]}{(\nu_2-4j+4)}$

(a) For arbitrary measures, Stieltjes procedure was used to calculate a_{ij}, b_{ij}

NEW X-PDD METHOD

- Second-Moment Statistics

$$\mathbb{E}[\tilde{y}_S(\mathbf{X})] = y_0 := \int_{\mathbb{R}^N} y(\mathbf{x})f_{\mathbf{X}}(\mathbf{x})d\mathbf{x} \\ \mathbb{E}[\tilde{y}_S(\mathbf{X}) - y_0]^2 = \sum_{s=1}^S \left(\sum_{i_1, \dots, i_S=1; i_1 < i_2 < \dots < i_S} \sum_{j_1=1}^m \dots \sum_{j_S=1}^m C_{i_1 \dots i_S j_1 \dots j_S} \right)$$

- Probability of Failure (Reliability)

$$P_{\theta}[\mathbf{X} \in \Omega_{F,k}] \cong P_{\theta}[\mathbf{X} \in \bar{\Omega}_{F,k}] = \lim_{L \rightarrow \infty} \frac{1}{L} \sum_{l=1}^L I_{\Omega_{F,k}}(\mathbf{x}^{(l)})$$

$\bar{\Omega}_{F,k} = S\text{-variate PDD approximation of } \Omega_{F,k}$

$\mathbf{x}^{(l)} = l\text{th sample of } \mathbf{X}; I_{\Omega_{F,k}}(\mathbf{x}) = \text{indicator function}$

- First two moments provide exact or convergent solutions
- Higher-order moments can be derived, but are less simple

RESULTS

- Second-Moment Properties of Stresses

<i>m</i>	Univariate PDD		Bivariate PDD		Crude MCS	
	Mean	S.D.	FEA	Mean	S.D.	FEA
(a) Maximum von Mises stress ($\sigma_{e,\max}$), MPa	510.51	132.68	25	510.53	132.88	277
2	510.51	132.68	33	510.57	132.92	481
3	0.253	0.065	25	0.253	0.065	254

Computational Cost

Univariate PDD (25-33 FEA); Bivariate PDD (277-481 FEA); Crude MCS (5000 FEA)

INTRODUCTION

Project Goal

Create new theoretical foundations and numerical algorithms of RBDO methods for large-scale design optimization of complex engineering systems

Project Objectives

- Develop new extended polynomial dimensional decomposition (X-PDD) method for reliability analysis of high-dimensional complex systems (Year 1)
- Integrate X-PDD and score functions for concurrent design sensitivity analysis (Year 2)
- Develop fast and efficient reliability-based and robust design optimization algorithms (Year 3)

(Project started in April 1, 2010)

NEW X-PDD METHOD

- Measure-Consistent Gauss Quadrature Formula (Golub & Welsch, 1969)

$$\int_{\mathbb{R}} g_i(x_i) dF_i(x_i) = \int_{\mathbb{R}} g_i(x_i) f_i(x_i) dx_i = \sum_{j=1}^n w_i^{(j)} g_i(x_i^{(j)}) + R_{in}(g_i)$$

$$J_{in} := \begin{bmatrix} a_{i0} & \sqrt{b_{i1}} & 0 & 0 & \dots & 0 & 0 \\ \sqrt{b_{i1}} & a_{i1} & \sqrt{b_{i2}} & 0 & \dots & 0 & 0 \\ 0 & \sqrt{b_{i2}} & a_{i2} & \sqrt{b_{i3}} & \dots & 0 & 0 \\ 0 & 0 & \sqrt{b_{i3}} & \ddots & \ddots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \sqrt{b_{i,n-2}} & 0 \\ 0 & 0 & 0 & 0 & \sqrt{b_{i,n-2}} & a_{in-2} & \sqrt{b_{i,n-1}} \\ 0 & 0 & 0 & 0 & 0 & \sqrt{b_{i,n-1}} & a_{in-1} \end{bmatrix}$$

- Possesses algebraic degree of exactness $2n-1$
- Obtaining eigensolutions of the Jacobi matrix is trivial

NEW X-PDD METHOD

- Dimensional Decomposition (Hoeffding, 1948)

Input $\mathbf{X} \in \mathbb{R}^N \rightarrow$ NONLINEAR SYSTEM \rightarrow Output $y(\mathbf{X}) \in \mathbb{R}$

$$(\Omega, \mathcal{F}) \xrightarrow{X} (\mathbb{R}^N, \mathcal{B}^N) \xrightarrow{y} (\mathbb{R}, \mathcal{B})$$

$$y(\mathbf{X}) = y_0 + \sum_{i=1}^N y_i(X_i) + \sum_{i_1, i_2=1; i_1 < i_2}^N y_{i_1 i_2}(X_{i_1}, X_{i_2}) + \dots + \sum_{i_1, \dots, i_s=1; i_1 < \dots < i_s}^N y_{i_1 \dots i_s}(X_{i_1}, \dots, X_{i_s}) + \dots + y_{12 \dots N}(X_1, \dots, X_N)$$

$$\tilde{y}_S(\mathbf{X}) = y_0 + \sum_{i=1}^N y_i(X_i) + \underbrace{\sum_{i_1, i_2=1; i_1 < i_2}^N y_{i_1 i_2}(X_{i_1}, X_{i_2}) + \dots + \sum_{i_1, \dots, i_s=1; i_1 < \dots < i_s}^N y_{i_1 \dots i_s}(X_{i_1}, \dots, X_{i_s})}_{S\text{-variate approximation of } y(\mathbf{X})}$$

NEW X-PDD METHOD

- S -variate, m -th order PDD Approximation

$$\tilde{y}_S(\mathbf{X}) = y_0 + \sum_{i=1}^N \sum_{j=1}^m C_{ij} \psi_{ij}(X_i) + \sum_{i_1, i_2=1; i_1 < i_2}^N \sum_{j_1=1}^m \sum_{j_2=1}^m C_{i_1 i_2 j_1 j_2} \prod_{k=1}^2 \psi_{i_k j_k}(X_{i_k}) + \dots + \sum_{i_1, \dots, i_s=1; i_1 < \dots < i_s}^N \sum_{j_1=1}^m \dots \sum_{j_s=1}^m C_{i_1 \dots i_s j_1 \dots j_s} \prod_{k=1}^s \psi_{i_k j_k}(X_{i_k})$$

$$y_{i_1 \dots i_s}(X_{i_1}, \dots, X_{i_s}) = \sum_{j_1=1}^{\infty} \dots \sum_{j_s=1}^{\infty} C_{i_1 \dots i_s j_1 \dots j_s} \prod_{k=1}^s \psi_{i_k j_k}(X_{i_k})$$

$$C_{i_1 \dots i_s j_1 \dots j_s} = \int_{\mathbb{R}^N} y(\mathbf{x}) \prod_{k=1}^s \psi_{i_k j_k}(x_{i_k}) f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x}, 1 \leq s \leq N$$

NEW X-PDD METHOD

- Measure-Consistent ON Polynomial Basis

$\mathbf{X} = \{X_1, \dots, X_N\}^T$; indep.; $X_i \sim f_i(x_i)$ on $(\Omega_i, \mathcal{F}_i, P_i)$

$$\mathcal{L}_2(\Omega_i, \mathcal{F}_i, P_i) := \left\{ y_i(x_i) : \int_{\mathbb{R}} y_i^2(x_i) f_i(x_i) dx_i < \infty \right\}$$

Hilbert space

$\{\psi_{ij}(x_i); j = 0, 1, \dots\} \rightarrow$ a set of ON bases in $\mathcal{L}_2(\Omega_i, \mathcal{F}_i, P_i)$

Two Important Properties of $\psi_{ij}(X_i)$:

$$\mathbb{E}_{P_i}[\psi_{ij}(X_i)] = \int_{\mathbb{R}} \psi_{ij}(x_i) f_i(x_i) dx_i = \begin{cases} 1, & \text{if } j = 0 \\ 0, & \text{if } j \neq 0 \end{cases}$$

$$\mathbb{E}_{P_i}[\psi_{ij_1}(X_i) \psi_{ij_2}(X_i)] = \int_{\mathbb{R}} \psi_{ij_1}(x_i) \psi_{ij_2}(x_i) f_i(x_i) dx_i = \begin{cases} 1, & \text{if } j_1 = j_2 \\ 0, & \text{if } j_1 \neq j_2 \end{cases}$$

NEW X-PDD METHOD

- Dimension-Reduction Integration for Coefficients

$$\hat{y}_R(\mathbf{x}) = \sum_{k=0}^R (-1)^k \binom{N-R+k-1}{k} \sum_{i_1, \dots, i_R-k=1; i_1 < i_2 < \dots < i_{R-k}}^N \times$$

$$\int_{\mathbb{R}^{R-k}} y(c_{i_1}, \dots, c_{i_{R-k}}, c_{i_1+1}, \dots, c_{i_{R-k}+1}, \dots, c_N) \prod_{p=1}^R \psi_{i_p j_p}(x_{i_p}) \prod_{p=1}^k f_{x_p}(x_{i_p}) dx_{i_p}$$

- Highly efficient when $R \ll N$ (also convergent)
- When $R = 1, 2$, or 3 , requires one-, at most two-, and at most three-dimensional integrations, respectively

RESULTS

- Example 1: A Polynomial Function

$$y(\mathbf{X}) = 500 - (X_1 + X_2)^3 + X_1 - X_2 - X_3 + X_1 X_2 X_3 - X_4$$

$$X_i, i = 1, \dots, 4$$